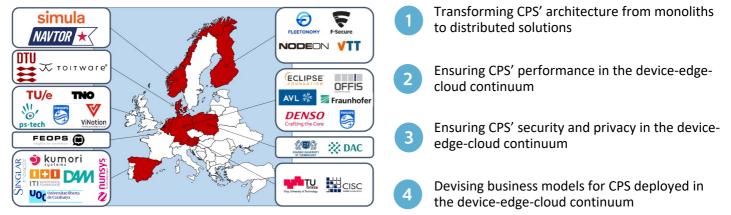




Towards safe and secure distributed cyber-physical systems

The overarching goal of the TRANSACT project is to develop a universal, distributed solution architecture for the transformation of safety-critical cyber-physical systems, from localised standalone systems into safe and secure distributed solutions leveraging edge and cloud computing.



Coordinator: PHILIPS MEDICAL SYSTEMS



UC1: Remote operation of autonomous vehicles for the navigation in urban environments

Industrial use cases



UC2: Critical maritime decision support enhanced by distributed, AI enhanced edge and cloud solutions



UC3: Cloud-featured battery management systems



UC4: Edge-cloud-based clinical applications platform for Image Guided Therapy and diagnostic imaging systems



UC5: Critical wastewater treatment decision support enhanced by distributed, AI enhanced edge and cloud solutions

TRANSACT has received funding from the KDT Joint Undertaking (JU) under grant agreement No 101007260. The JU receives support from the European Union's Horizon 2020 research and innovation programme and Netherlands, Finland, Germany, Poland, Austria, Spain, Belgium. Denmark, Norway.

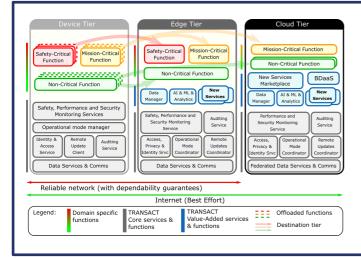






Towards safe and secure distributed cyber-physical systems

The overarching goal of the TRANSACT project is to develop a universal, distributed solution architecture for the transformation of safety-critical cyber-physical systems, from localised standalone systems into safe and secure distributed solutions leveraging edge and cloud computing.



TRANSACT technological innovations:

- Extend the existing edge/cloud technologies, to support safety-critical CPS and enable a continuous deployment of functions
- Extend model-based and simulation-based design tools to support the correct integration and deployment of safety-critical components
- Develop dynamic end-to-end safety and performance monitoring systems, load balancing mechanisms and graceful degradation strategies
- Implement end-to-end security and privacy technologies based on both theoretical (by design) and actual (monitoring) scenarios
- Develop techniques for the virtual design, implementation, certification and early integration of large distributed CPS
- Integrate AI based services and data analytics services into safety-critical CPS.

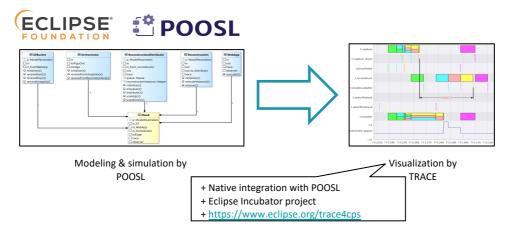
Eclipse POOSL for early system validation

Parallel Object-Oriented Specification Language (POOSL)

- Light-weight modeling and simulation for early system validation
- Successful applications in high-tech companies

Eclipse Open-Source Project

- Eclipse Modeling Project for model-based development technologies
- Research result from TU/e and ESI, industrialised by Obeo
- POOSL website: <u>https://poosl.org</u>



TRANSACT has received funding from the KDT Joint Undertaking (JU) under grant agreement No 101007260. The JU receives support from the European Union's Horizon 2020 research and innovation programme and Netherlands, Finland, Germany, Poland, Austria, Spain, Belgium. Denmark, Norway.

